



Relations Between Principal Eigenvalue and Torsional Rigidity with Robin Boundary Conditions

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Abstract. We consider the torsional rigidity and the principal eigenvalue related to the Laplace operator with Dirichlet and Robin boundary conditions. The goal is to find upper and lower bounds to products of suitable powers of the quantities above in the class of Lipschitz domains. The threshold exponent for the Robin case is explicitly recovered and shown to be strictly smaller than in the Dirichlet one.

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1. Introduction

Elliptic boundary value problems involving Robin boundary conditions share many structural and analytical similarities with those formulated under Dirichlet boundary conditions. Nevertheless, the Robin case also exhibits distinct and subtle phenomena that are of considerable mathematical and physical interest. In the present article, we focus on exploring the relations between two fundamental quantities associated with the Laplace operator under Robin conditions: the principal (or first) eigenvalue and the torsional rigidity of a domain.

Throughout the paper, we denote by Ω an open bounded subset of $\mathbb{R}^d$ with a sufficiently regular boundary (for instance of Lipschitz class). Its Lebesgue measure is denoted by $|\Omega|$, and without loss of generality we shall assume that $|\Omega| = 1$ in order to simplify the presentation.

Let $\beta > 0$ be the Robin parameter, the *first eigenvalue* $\lambda_\beta(\Omega)$ of the Laplacian with Robin boundary conditions is defined as the smallest λ for which the boundary

value problem

$$\begin{cases} -\Delta u = \lambda u & \text{in } \Omega \\ \partial_\nu u + \beta u = 0 & \text{on } \partial\Omega \end{cases}$$

admits a nontrivial solution, where ∂_ν denotes the outward normal derivative on $\partial\Omega$. Equivalently (see for instance [10, Section 4.2]), $\lambda_\beta(\Omega)$ can be characterized variationally as the minimum of the associated Rayleigh quotient

$$\lambda_\beta(\Omega) = \min \left\{ \frac{\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1}}{\int_\Omega u^2 dx} : u \in H^1(\Omega) \setminus \{0\} \right\}, \quad (1.1)$$

where $\mathcal{H}^{d-1}$ denotes the Hausdorff $d-1$ dimensional measure.

The second quantity of interest is the *torsional rigidity* $T_\beta(\Omega)$ which, in the context of elasticity theory, represents the resistance of the domain Ω to torsion under boundary conditions of Robin type. It is defined by

$$T_\beta(\Omega) = \int_\Omega w_\beta dx,$$

where w_β denotes the unique weak solution of the Poisson problem

$$\begin{cases} -\Delta u = 1 & \text{in } \Omega \\ \partial_\nu u + \beta u = 0 & \text{on } \partial\Omega. \end{cases}$$

We refer to [1] for an extended presentation of problems involving the Robin torsional rigidity. Equivalently (see for instance [10, Subsection 4.5.1.2]), $T_\beta(\Omega)$ admits the variational representation

$$T_\beta(\Omega) = \max \left\{ \frac{(\int_\Omega u dx)^2}{\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1}} : u \in H^1(\Omega) \setminus \{0\} \right\}. \quad (1.2)$$

When $\beta = +\infty$ the Robin condition degenerates into the Dirichlet condition $u = 0$ on $\partial\Omega$. In this limit, the corresponding quantities $\lambda_\infty(\Omega)$ and $T_\infty(\Omega)$ reduce to the classical Dirichlet principal eigenvalue and Dirichlet torsional rigidity respectively, and the minimization problems (1.1) and (1.2) are naturally restricted to the Sobolev space $H_0^1(\Omega)$. It is well known (see for instance [10, Proposition 4.5] for the eigenvalue and [16, Theorem 3.1] with $f \equiv 1$ for the torsional rigidity) that

$$\lim_{\beta \rightarrow +\infty} \lambda_\beta(\Omega) = \lambda_\infty(\Omega) \quad \text{and} \quad \lim_{\beta \rightarrow +\infty} T_\beta(\Omega) = T_\infty(\Omega). \quad (1.3)$$

Our main goal is to investigate shape optimization problems involving the interaction between these two fundamental quantities. For an overview on shape optimization problems we refer to the books [9], [22] and [23]. Specifically, for a fixed $\beta > 0$ and a given real exponent $q > 0$ we consider shape functionals of the form

$$F_{\beta,q}(\Omega) = \lambda_\beta(\Omega) T_\beta^q(\Omega). \quad (1.4)$$

We are particularly interested in determining the extremal values of the functional $F_{\beta,q}$ among all domains Ω of fixed measure:

$$\begin{cases} m_{\beta,q} = \inf \{ F_{\beta,q}(\Omega) : |\Omega| = 1 \} \\ M_{\beta,q} = \sup \{ F_{\beta,q}(\Omega) : |\Omega| = 1 \}. \end{cases} \quad (1.5)$$

In the following, since the Robin parameter β is fixed, we often omit it from the notation and simply write F_q , m_q , M_q .

The Dirichlet case corresponding to $\beta = +\infty$ has been extensively analyzed in [7] and [8] (see also [2], [3]). In the present work, we turn our attention to the more delicate situation where $\beta < +\infty$, and we highlight an interesting phenomenon that emerges in this regime. Indeed, while it is known that $m_{\infty,q} = 0$ if and only if $q > 2/(d+2)$, we establish that $m_{\beta,q} = 0$ if and only if $q > 1/(d+1)$, independently of the value of β , in spite of the asymptotic behavior described in (1.3).

As for the Dirichlet boundary condition, the case $q = 1$ deserves particular attention. Indeed, we prove that $M_1 = 1$ by carrying out a detailed analysis of the asymptotic behavior of solutions in appropriately and finely perforated domains. This result is similar to what is known in the Dirichlet setting. However, in the Robin case the characteristic size of the perforations is different, which leads to a different scaling, even though the final conclusion remains the same.

The combination of Theorems 4.1 and 4.3 allows us to bound from below and from above the first Robin eigenvalue $\lambda_\beta(\Omega)$, or equivalently the principal frequency of a membrane Ω elastically supported along its boundary, in terms of powers of the corresponding Robin energy. More precisely

$$mT_\beta(\Omega)^{-\frac{1}{d+1}} \leq \lambda_\beta(\Omega) \leq T_\beta(\Omega)^{-1}$$

for a suitable positive constant m and for every domain Ω with $|\Omega| = 1$. It is interesting to notice that the upper bound is analogous to the one of the Dirichlet case, while the lower bound has a different optimal power.

The paper is organized as follows. In Sect. 2, we recall some preliminary analytical results and technical tools that will be employed in the subsequent analysis. Section 3 is devoted to the Dirichlet case $\beta = +\infty$, for which several sharp results are already known; we summarize and reinterpret them in a unified framework. In Sect. 4, we turn to the Robin case $\beta < +\infty$, which presents new challenges and a richer phenomenology. Finally, in Sect. 5 we conclude by outlining a number of open problems and conjectures that, in our view, deserve further investigation.

2. Preliminary Results

If we consider λ_β or T_β only, the related optimization problems are well-known and we have the following results. Here and in the following we denote by B a ball in $\mathbb{R}^d$ with unitary Lebesgue measure.

- We have $\lambda_\infty(B) \leq \lambda_\infty(\Omega)$ for every Ω with $|\Omega| = 1$. This inequality is known as *Faber–Krahn inequality*.
- We have $T_\infty(B) \geq T_\infty(\Omega)$ for every Ω with $|\Omega| = 1$. This inequality is known as *Saint-Venant inequality*.
- We have for every $\beta < +\infty$ $\lambda_\beta(B) \leq \lambda_\beta(\Omega)$ for every Ω with $|\Omega| = 1$. This inequality was proved in [5] in the case $d = 2$ and in [20] for any dimension d . In [11] the same result is obtained by means of a free discontinuity approach in spaces of functions of bounded variation.

- We have for every $\beta < +\infty$

$$T_\beta(B) \geq T_\beta(\Omega) \quad \text{for every } \Omega \text{ with } |\Omega| = 1. \quad (2.1)$$

This inequality was proved in [11].

The main difference between the Dirichlet case $\beta = +\infty$ and the Robin case $\beta < +\infty$ is in the scaling properties. We have for every scaling factor $t > 0$

$$\begin{cases} \lambda_\infty(t\Omega) = t^{-2}\lambda_\infty(\Omega) \\ T_\infty(t\Omega) = t^{d+2}T_\infty(\Omega), \end{cases}$$

while, if $\beta < +\infty$ we have

$$\begin{cases} \lambda_\beta(t\Omega) = t^{-2}\lambda_{t\beta}(\Omega) \\ T_\beta(t\Omega) = t^{d+2}T_{t\beta}(\Omega). \end{cases} \quad (2.2)$$

An easy comparison, by using either $H_0^1(\Omega)$ or constant test functions, gives for every Ω

$$\begin{cases} \lambda_\beta(\Omega) \leq \lambda_\infty(\Omega) \wedge \beta \frac{\mathcal{H}^{d-1}(\partial\Omega)}{|\Omega|} \\ T_\beta(\Omega) \geq T_\infty(\Omega) \vee \frac{|\Omega|^2}{\beta \mathcal{H}^{d-1}(\partial\Omega)}. \end{cases}$$

In particular, for a ball B_r of radius r we have

$$\begin{cases} \lambda_\beta(B_r) \leq r^{-2}\lambda_\infty(B_1) \wedge r^{-1}\beta d \\ T_\beta(B_r) \geq r^{d+2}T_\infty(B_1) \vee r^{d+1}\frac{\omega_d}{d}, \end{cases}$$

where ω_d denotes the Lebesgue measure of the unit ball in $\mathbb{R}^d$. Some more precise estimates hold, as recalled below.

Proposition 2.1. *For every $r > 0$ we have:*

$$\frac{\beta}{4r(1+\beta r)} \leq \lambda_\beta(B_r) \leq \frac{C_d\beta}{r(1+\beta r)} \quad (2.3)$$

where C_d is a constant depending only on the dimension d , and

$$T_\beta(B_r) = \frac{\omega_d}{d} \left(\frac{r^{d+1}}{\beta} + \frac{r^{d+2}}{d+2} \right). \quad (2.4)$$

Proof. Estimates (2.3) can be found in [27], while equality (2.4) comes by a direct computation in polar coordinates. $\square$

We recall the classical Gagliardo–Nirenberg inequality in $H^1(\mathbb{R}^d)$:

$$\|u\|_{L^2(\mathbb{R}^d)} \leq C \|\nabla u\|_{L^2(\mathbb{R}^d)}^\theta \|u\|_{L^1(\mathbb{R}^d)}^{1-\theta} \quad \text{for every } u \in H^1(\mathbb{R}^d), \quad (2.5)$$

where $\theta = d/(d+2)$ and C is a constant that depends only on the dimension d . The inequality above clearly holds for functions $u \in H_0^1(\Omega)$.

In the following we need a variant of the Gagliardo–Nirenberg inequality above for functions in $H^1(\Omega)$; we recall the inequality below, as obtained in [29].

Theorem 2.2. *For every open bounded subset Ω of $\mathbb{R}^d$ with a Lipschitz boundary there exists a constant $C > 0$ such that*

$$\int_{\Omega} u^2 dx \leq C \left[\int_{\Omega} |\nabla u|^2 dx + \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1} \right]^{d/(d+1)} \left[\int_{\Omega} |u| dx \right]^{2/(d+1)}$$

for all $u \in H^1(\Omega) \cap L^1(\Omega)$. Moreover, the constant C depends only on d and on $|\Omega|$.

Proof. See Proposition 4.2.9 of [29]. $\square$

3. The Case of Dirichlet Boundary Conditions

The optimization problems for the shape functionals F_q in (1.4) have been extensively studied in the Dirichlet case $\beta = +\infty$. We recall in the present section the most important results and we refer to [15] for a general result on shape optimization problems with Dirichlet boundary conditions. We start by the minimization problem in (1.5).

Theorem 3.1. *In the case $\beta = +\infty$ the following facts hold for the quantity m_q in (1.5):*

- for every $q > 2/(d+2)$ we have $m_q = 0$;
- for every $q \leq 2/(d+2)$ we have $m_q > 0$; in addition, the value m_q is reached by the ball B .

Proof. The first assertion can be proved by taking as Ω the disjoint union of a ball B_δ and of N balls B_ε , with $\delta > \varepsilon$ and $\omega_d(\delta^d + N\varepsilon^d) = 1$. We have

$$\begin{aligned} F_q(\Omega) &= \delta^{-2} \lambda_\infty(B_1) \left((\delta^{d+2} + N\varepsilon^{d+2}) T_\infty(B_1) \right)^q \\ &= F_q(B_1) \delta^{-2} (\delta^{d+2} + \varepsilon^2(1/\omega_d - \delta^d))^q. \end{aligned}$$

By taking $\varepsilon^2 \ll \delta^{d+2}$ we obtain

$$F_q(\Omega) \approx F_q(B_1) \delta^{-2+q(d+2)},$$

and the first assertion is proved by passing to the limit as $\delta \rightarrow 0$.

For the second assertion, the equality $m_q = F_q(B)$ when $q \leq 2/(d+2)$ was proved in [25] and [26]; for an extension to some nonlinear cases we refer to [6]. We give here a simple proof of the inequality $m_q > 0$, that can be obtained by the Gagliardo–Nirenberg inequality (2.5). In fact, if u is a first eigenfunction of $-\Delta$ with Dirichlet boundary conditions, by the definition (1.2) of T_∞ we obtain

$$\begin{aligned} F_q(\Omega) &\geq \frac{\int_{\Omega} |\nabla u|^2 dx}{\int_{\Omega} |u|^2 dx} \left(\frac{(\int_{\Omega} u dx)^2}{\int_{\Omega} |\nabla u|^2 dx} \right)^q \\ &= \left(\frac{\|\nabla u\|_{L^2(\Omega)}^{1-q} \|u\|_{L^1(\Omega)}^q}{\|u\|_{L^2(\Omega)}} \right)^2. \end{aligned}$$

By the Gagliardo–Nirenberg inequality (2.5) we have

$$\begin{aligned}\sqrt{F_q(\Omega)} &\geq \frac{1}{C} \left(\frac{\|\nabla u\|_{L^2(\Omega)}}{\|u\|_{L^1(\Omega)}} \right)^{1-q-\theta} \\ &= \frac{1}{C} (\lambda_\infty(\Omega))^{(1-q-\theta)/2} \left(\frac{\|u\|_{L^2(\Omega)}}{\|u\|_{L^1(\Omega)}} \right)^{1-q-\theta}.\end{aligned}$$

Now, the Faber-Krahn inequality, the fact that $1 - q - \theta \geq 0$, and the Hölder inequality, give

$$\sqrt{F_q(\Omega)} \geq \frac{1}{C} (\lambda_\infty(B))^{(1-q-\theta)/2}.$$

Hence, taking the infimum over all Ω with $|\Omega| = 1$, gives

$$m_q \geq \frac{1}{C^2} (\lambda_\infty(B))^{1-q-\theta},$$

as required. $\square$

We now pass to the quantity M_q in (1.5).

Theorem 3.2. *In the case $\beta = +\infty$ the following facts hold for the quantity M_q in (1.5):*

- for every $q < 1$ we have $M_q = +\infty$;
- for $q = 1$ we have $M_q = 1$;
- for every $q > 1$ we have $M_q < +\infty$;
- there exists $\bar{q} > 1$ such that for every $q \geq \bar{q}$ the value M_q is reached by the ball B .

Proof. The first assertion follows by taking as Ω the disjoint union on N balls B_ε , with $\omega_d N \varepsilon^d = 1$. This gives

$$F_q(\Omega) = \varepsilon^{-2} \lambda_\infty(B_1) (N \varepsilon^{d+2} T_\infty(B_1))^q = F_q(B_1) \varepsilon^{-2+2q},$$

so that, passing to the limit as $\varepsilon \rightarrow 0$, we have $M_q = +\infty$ when $q < 1$.

In the second assertion, to prove that $M_1 \leq 1$ it is enough to consider the solution w of the PDE

$$\begin{cases} -\Delta u = 1 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

and take it as a test function for λ_∞ . This gives

$$F_1(\Omega) \leq \frac{\int_\Omega |\nabla w|^2 dx}{\int_\Omega w^2 dx} \frac{(\int_\Omega w dx)^2}{\int_\Omega |\nabla w|^2 dx} = \frac{(\int_\Omega w dx)^2}{\int_\Omega |w|^2 dx}$$

and, by Hölder inequality, we conclude that $M_1 \leq 1$. The proof that $M_1 = 1$ is more delicate and we refer to [4]; a simpler proof, that uses capacitary measures (for which we refer to [9]), can be found in [8].

To prove the third assertion it is enough to write

$$F_q(\Omega) = F_1(\Omega) (T_\infty(\Omega))^{q-1}.$$

By the inequality $F_1(\Omega) \leq 1$ and the Saint-Venant inequality $T_\infty(\Omega) \leq T_\infty(B)$, we obtain

$$F_q(\Omega) \leq (T_\infty(B))^{q-1},$$

so that $M_q \leq (T_\infty(B))^{q-1}$.

For the last assertion we refer to [7], where this property was conjectured under the name of *reverse Kohler–Jobin inequality*, and to [14], where it was proved. $\square$

4. The Case of Robin Boundary Conditions

In this section we consider the Robin case $\beta < +\infty$. We start by studying the case of m_q .

Theorem 4.1. *In the case $\beta < +\infty$ the following facts hold for the quantity m_q in (1.5):*

- for every $q > 1/(d+1)$ we have $m_q = 0$;
- for every $q \leq 1/(d+1)$ we have $m_q > 0$.

Proof. The first assertion can be proved by taking as Ω the disjoint union of a ball B_δ and of N balls B_ε , with $\delta > \varepsilon$ and $\omega_d(\delta^d + N\varepsilon^d) = 1$. We have by (2.3) and (2.4)

$$\begin{aligned} F_q(\Omega) &\approx \delta^{-1} \left((\delta^{d+1} + N\varepsilon^{d+1}) \right)^q \\ &= \delta^{-1} (\delta^{d+1} + \varepsilon(1/\omega_d - \delta^d))^q. \end{aligned}$$

By taking $\varepsilon \ll \delta^{d+1}$ we obtain

$$F_q(\Omega) \approx \delta^{-1+q(d+1)},$$

and the first assertion is proved by passing to the limit as $\delta \rightarrow 0$.

For the second assertion, by the definition of the torsional rigidity T_β , denoting by u the first eigenfunction of $-\Delta$ with Robin boundary condition on $\partial\Omega$, we have

$$\begin{aligned} F_{\beta,q}(\Omega) &\geq \frac{\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1}}{\int_\Omega u^2 dx} \left[\frac{(\int_\Omega u dx)^2}{\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1}} \right]^q \\ &= \frac{[\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1}]^{1-q} [\int_\Omega u dx]^{2q}}{\int_\Omega u^2 dx}. \end{aligned}$$

If $q = 1/(d+1)$, using Theorem 2.2 we have

$$\int_\Omega u^2 dx \leq C_\beta \left[\int_\Omega |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1} \right]^{d/(d+1)} \left[\int_\Omega u dx \right]^{2/(d+1)}$$

with a constant $C_\beta > 0$ which does not depend on Ω when $|\Omega| = 1$. Precisely, if C denotes the constant of Theorem 2.2, we may take

$$C_\beta = C(\beta \wedge 1)^{-\frac{d}{d+1}}.$$

If $q < 1/(d+1)$ we have, by the Saint-Venant inequality stating the optimality of B for the Robin torsional rigidity (see (2.1)),

$$F_{\beta,q}(\Omega) = F_{\beta,1/(d+1)}(\Omega) [T_\beta(\Omega)]^{q-1/(d+1)} \geq F_{\beta,1/(d+1)}(\Omega) [T_\beta(B)]^{q-1/(d+1)},$$

and the assertion now follows from the case $q = 1/(d+1)$. $\square$

Remark 4.2. Notice the difference between the threshold $2/(d+2)$ of the case $\beta = +\infty$ and $1/(d+1)$ of the case $\beta < +\infty$. Then, for $1/(d+1) < q \leq 2/(d+2)$ we have $m_{\beta,q} = 0$ for every $\beta < +\infty$, while $m_{\infty,q} > 0$. This in spite of the fact that $\lambda_\beta(\Omega)$ and $T_\beta(\Omega)$ tend to $\lambda_\infty(\Omega)$ and $T_\infty(\Omega)$ respectively, as $\beta \rightarrow +\infty$, and so

$$\lim_{\beta \rightarrow +\infty} F_{\beta,q}(\Omega) = F_{\infty,q}(\Omega) \quad \text{for every } \Omega.$$

We now pass to consider the case of M_q . In the following theorem, we prove the finiteness of M_q for $q > 1$, and the equality $M_1 = 1$ that we obtain by means of homogenization. To do so, we construct a suitable sequence of smooth domains with a periodic lattice of smooth holes. We inform the reader that some parts of the following proof, namely the estimate on the eigenvalues (4.3), could also be deduced within the abstract framework devised in [24, Theorem 1] (which can be seen as the Robin counterpart of the classical results in [17]); nevertheless, we give an independent complete proof for the sake of self-containment.

Theorem 4.3. *In the case $\beta < +\infty$ the following facts hold for the quantity M_q in (1.5):*

- for every $q < 1$ we have $M_q = +\infty$;
- for $q = 1$ we have $M_q = 1$;
- for every $q > 1$ we have $M_q < +\infty$.

Proof. The first assertion follows by taking as Ω the disjoint union on N balls B_ε , with $\omega_d N \varepsilon^d = 1$. This gives by (2.3) and (2.4)

$$F_q(\Omega) \approx \varepsilon^{-1} (N \varepsilon^{d+1})^q \approx \varepsilon^{-2+2q},$$

so that, passing to the limit as $\varepsilon \rightarrow 0$, we have $M_q = +\infty$ when $q < 1$.

In the second assertion, to prove that $M_1 \leq 1$ it is enough to consider the solution w of the PDE

$$\begin{cases} -\Delta u = 1 & \text{in } \Omega \\ \partial_\nu u + \beta u = 0 & \text{on } \partial\Omega, \end{cases}$$

and take it as a test function for λ_β . This gives

$$F_1(\Omega) \leq \frac{\int_\Omega |\nabla w|^2 dx + \beta \int_{\partial\Omega} w^2 d\mathcal{H}^{d-1}}{\int_\Omega w^2 dx} \frac{(\int_\Omega w dx)^2}{\int_\Omega |\nabla w|^2 dx + \beta \int_{\partial\Omega} w^2 d\mathcal{H}^{d-1}} = \frac{(\int_\Omega w dx)^2}{\int_\Omega |w|^2 dx}$$

and, by Hölder inequality, we conclude that $M_1 \leq 1$.

In order to prove the third assertion it is enough to write

$$F_q(\Omega) = F_1(\Omega) T_\beta^{q-1}(\Omega) \leq M_1 T_\beta^{q-1}(\Omega)$$

and to use the inequality $M_1 \leq 1$ and $T_\beta(\Omega) \leq T_\beta(B)$ seen in Sect. 2.

It remains to prove that $M_1 \geq 1$, for which we have to construct a sequence Ω_n such that $\lim_n F_1(\Omega_n) \geq 1$.

We start considering a unit cube $Q_1 = (0, 1)^d$ perforated by small balls arranged on a periodic lattice. For $N \in \mathbb{N}$ let us subdivide Q_1 in a cubic grid of side $1/N$ and for $\vec{\ell} \in \{1, \dots, N\}^d$, let $x_{\vec{\ell}}$ denote the centers of the cubic cells. Remove now balls with center $x_{\vec{\ell}}$ and radius

$$r_N = \frac{k}{N^{d/(d-1)}}, \quad k > 0$$

and observe that, for N large enough, the balls above are disjoint and well contained in Q_1 . Let $\Omega_N^k = Q_1 \setminus \bigcup_{\vec{\ell}} B(x_{\vec{\ell}}, r_N)$ and define the surface measures

$$\mu_N = \sum_{\vec{\ell}} \mathcal{H}^{d-1} \llcorner_{\partial B(x_{\vec{\ell}}, r_N)}.$$

Observe that

$$\mu_N(\mathbb{R}^d) = k^{d-1} d\omega_d \quad (4.1)$$

where ω_d is the $\mathcal{L}^d$ -measure of the unit ball in $\mathbb{R}^d$. We now claim that

$$\mu_N \rightarrow \mu = k^{d-1} d\omega_d 1_{Q_1} \mathcal{L}^d \text{ in } H^{-1}(\mathbb{R}^d). \quad (4.2)$$

A proof of (4.2) is given in the appendix.

We now prove that

$$\liminf_{N \rightarrow \infty} \lambda_\beta(\Omega_N^k) \geq \beta k^{d-1} d\omega_d. \quad (4.3)$$

To do this, consider the L^2 -normalized eigenfunctions u_N of Ω_N^k (we omit the dependence on k to shorten the notation). We clearly prove (4.3) under the nonrestrictive assumption that $\sup_N \lambda_\beta(\Omega_N^k) < +\infty$.

Step 1. We extend $(u_N)_N$ to a bounded sequence $(\tilde{u}_N)_N \subset H^1(Q_1)$. To do so, we construct a vector field $V_N \in C_c^1(Q_1; \mathbb{R}^d)$, which on each periodicity cell is such that

$$V_N(x) = x - x_{\vec{\ell}} \text{ on } B(x_{\vec{\ell}}, r_N), \quad V_N = 0 \text{ outside } B\left(x_{\vec{\ell}}, \frac{1}{2N}\right).$$

This vector field can be constructed to have uniformly bounded Lipschitz constant with respect to N : indeed, a radial cut-off function between a ball of radius $k/N^{\frac{d}{d-1}}$ and the one of radius $1/2N$ has derivative of order N , while $|x - x_{\vec{\ell}}| \leq \frac{\sqrt{d}}{2N}$ on each cell. We now use the Rellich–Pohozaev identity

$$\begin{aligned} & \int_{\Omega_N^k} \left[(\operatorname{div} V_N) \left(\frac{1}{2} |\nabla u_N|^2 - \lambda_\beta \frac{u_N^2}{2} \right) - (\nabla u_N \otimes \nabla u_N) : \nabla V_N \right] dx \\ &= \int_{\partial \Omega_N^k} \left[\partial_\nu u_N (V_N \cdot \nabla u_N) - \left(\frac{1}{2} |\nabla u_N|^2 - \lambda_\beta \frac{u_N^2}{2} \right) (V_N \cdot \nu) \right] d\mathcal{H}^{d-1}, \end{aligned}$$

which can be proved testing the equation $-\Delta u_N = \lambda_\beta u_N$ with $V \cdot \nabla u_N$ and integrating by parts, also using the equality

$$\nabla u_N \cdot ((D^2 u_N) V) = \frac{1}{2} V \cdot \nabla (|\nabla u_N|^2).$$

Recall that, on $\partial B(x_{\vec{\ell}}, r_N)$ one has

$$V_N(x) = (x - x_{\vec{\ell}}), \quad V_N \cdot \nu = (x - x_{\vec{\ell}}) \cdot \nu = -|x - x_{\vec{\ell}}| = -\frac{k}{N^{\frac{d}{d-1}}}.$$

Furthermore

$$V_N \cdot \nabla u_N = (x - x_{\vec{\ell}}) \cdot \nabla u_N = -\frac{k}{N^{\frac{d}{d-1}}} \partial_\nu u_N.$$

No term on ∂Q_1 appears, as $V_N = 0$ on ∂Q_1 . Using Robin boundary conditions $\partial_\nu u_N = -\beta u_N$, the equality then becomes

$$\begin{aligned} & \int_{\Omega_N^k} \left[(\operatorname{div} V_N) |\nabla u_N|^2 - 2 (\nabla u_N \otimes \nabla u_N) : \nabla V_N - \lambda_\beta (\operatorname{div} V_N) u_N^2 \right] dx \\ &= \sum_{\tilde{\ell} \in \{1, \dots, N\}^d} \int_{\partial B(x_{\tilde{\ell}}, r_N)} -\frac{k}{N^{\frac{d}{d-1}}} \left[|\nabla_\tau u_N|^2 + \frac{\beta^2 - \lambda_\beta}{N^{\frac{d}{d-1}}} u_N^2 \right] d\mathcal{H}^{d-1}. \end{aligned}$$

Now, the eigenfunctions are normalized in L^2 , and we assume the eigenvalues (and hence the Robin form) to be uniformly bounded; furthermore, V_N are bounded in C^1 . We therefore get the existence of a constant C depending on $d, k, \sup_N \lambda_\beta(\Omega_N^k)$, and β such that

$$\sum_{\tilde{\ell} \in \{1, \dots, N\}^d} \int_{\partial B(x_{\tilde{\ell}}, r_N)} |\nabla_\tau u_N|^2 d\mathcal{H}^{d-1} \leq C N^{\frac{d}{d-1}} = \frac{C}{r_N}.$$

Define $\tilde{u}_N$ as the harmonic extension inside each ball; it holds the estimate (see for instance [21, Page 20], which also hints at the proof of the inequality)

$$\int_{B(x_{\tilde{\ell}}, r_N)} |\nabla \tilde{u}_N|^2 dx \leq \frac{r_N}{d-1} \int_{\partial B(x_{\tilde{\ell}}, r_N)} |\nabla_\tau u_N|^2 d\mathcal{H}^{d-1},$$

whence

$$\sum_{\tilde{\ell} \in \{1, \dots, N\}^d} \int_{B(x_{\tilde{\ell}}, r_N)} |\nabla \tilde{u}_N|^2 dx \leq C.$$

Combining with the bound on $\|\nabla u_N\|_{L^2(\Omega_N^k)}$ yields that $\|\nabla \tilde{u}_N\|_{L^2(Q_1)}$ is bounded by a constant depending on $d, k, \sup_N \lambda_\beta(\Omega_N^k)$, and β . As we also have

$$\int_{\partial Q_1} u_N^2 d\mathcal{H}^{d-1} \leq \frac{\lambda_\beta(\Omega_N^k)}{\beta},$$

the claim is proved.

Step 2. We now consider the weak- $H^1(Q_1)$ limit u of the sequence $\tilde{u}_N$, which exists up to a subsequence, and prove the inequality

$$\liminf_{N \rightarrow \infty} \int_{Q_1} u_N^2 d\mu_N = \liminf_{N \rightarrow \infty} \int_{Q_1} \tilde{u}_N^2 d\mu_N \geq k^{d-1} d\omega_d \int_{Q_1} u^2 dx. \quad (4.4)$$

The first equality is trivial, as $u_N = \tilde{u}_N$ on the support of μ_N . As for the lower semicontinuity inequality, fix $M > 0$ and a smooth cutoff $0 \leq \phi \leq 1$. Then

$$\liminf_{N \rightarrow \infty} \int_{Q_1} \tilde{u}_N^2 d\mu_N \geq \liminf_{N \rightarrow \infty} \int_{Q_1} \min\{(\phi \tilde{u}_N)^2, M\} d\mu_N.$$

The truncations $\min\{(\phi \tilde{u}_N)^2, M\}$ converge weakly in H_0^1 to $\min\{(\phi u)^2, M\}$. Using (4.2) we then have:

$$\lim_{N \rightarrow \infty} \int_{Q_1} \min\{(\phi \tilde{u}_N)^2, M\} d\mu_N = \int_{Q_1} k^{d-1} d\omega_d \min\{(\phi u)^2, M\} dx.$$

Passing to the limit $\phi \uparrow 1$ and $M \rightarrow \infty$ gives (4.4).

Step 3. We prove (4.3). To this aim, it suffices to notice that, since the functions $\tilde{u}_N$ converge strongly to u in $L^2(Q_1)$, so do then $u_N 1_{\Omega_N^k}$ by Vitali's theorem. As the functions u_N are L^2 -normalized, it must then hold $\|u\|_{L^2(Q_1)} = 1$, so that (4.3) directly follows from Step 2.

Step 4. We finally prove $M_1 \geq 1$. To this, we first consider a sequence $t_N^k \downarrow 1$ so that $|t_N^k \Omega_N^k| = 1$ and observe that by the scaling property (2.2) we deduce

$$\lambda_\beta(t_N^k \Omega_N^k) \geq \frac{1}{(t_N^k)^2} \lambda_\beta(\Omega_N^k). \quad (4.5)$$

As for the torsion part, we trivially estimate with the test function $w = 1$, and together with (4.5) and (4.1) we get

$$F_\beta(t_N^k \Omega_N^k) \geq \frac{1}{(t_N^k)^{d+1}} \frac{\lambda_\beta(\Omega_N^k)}{\beta(\mathcal{H}^{d-1}(\partial Q_1) + k^{d-1} d\omega_d)}$$

With the liminf as $N \rightarrow +\infty$, using (4.3), we have

$$M_1 \geq \frac{\beta k^{d-1} d\omega_d}{\beta(\mathcal{H}^{d-1}(\partial Q_1) + k^{d-1} d\omega_d)}$$

which entails the conclusion when $k \rightarrow +\infty$. $\square$

Remark 4.4. An alternative proof of the inequality $M_1 \geq 1$ can be obtained by means of a γ -closure argument; we give a short sketch below.

We first observe that, since both λ_β and T_β are continuous with respect to the γ -convergence, we also have

$$M_1 = \sup \{F_1(\mu) : \mu \in \mathcal{M}\}$$

where $\mathcal{M}$ denotes the γ -closure of the class of open sets Ω with $|\Omega| = 1$. By approximating a smooth surface $\partial\Omega$ by means of very rough surfaces, as in Fig. 1, we obtain that the class $\mathcal{M}$ contains all the problems with a Dirichlet condition on $\partial\Omega$, hence also the class of γ -limits of Dirichlet problems. The γ -closure of Dirichlet problems has been fully identified in [19] as the class of capacitary measures, that is the measures that vanish on all sets of capacity zero. Then we have that $\mathcal{M}$ contains all the capacitary measures.

In fact the class $\mathcal{M}$ is strictly larger than the class of capacitary measures. To see this one could consider the case of smooth domains converging to a domain with a (possibly smooth) fracture (see, for instance, [11–13, 18]). More precisely, take a smooth surface S in an open set Ω , an ε neighborhood S_ε , and $\Omega_\varepsilon = \Omega \setminus S_\varepsilon$. We have that the Robin energies on the sets Ω_ε

$$\frac{1}{2} \int_{\Omega_\varepsilon} |\nabla u|^2 dx + \beta \int_{\partial\Omega_\varepsilon} u^2 d\mathcal{H}^{d-1}$$

Γ -converge (as $\varepsilon \rightarrow 0$) to the energy

$$\frac{1}{2} \int_{\Omega \setminus S} |\nabla u|^2 dx + \beta \int_{\partial\Omega} u^2 d\mathcal{H}^{d-1} + \beta \int_S (u_+^2 + u_-^2) d\mathcal{H}^{d-1},$$

which cannot be represented by a capacitary measure. In the expression above u_- and u_+ are the left and right traces of the Sobolev function u .

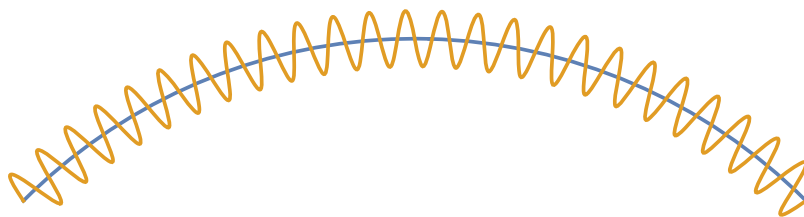


FIGURE 1 Approximation of a smooth boundary by means of rough boundaries

In particular, the γ -closure of Robin problems contains all the capacity measures $c \, dx$ with $c > 0$. Then, taking as Ω the ball B , we have that

$$M_1 \geq \lambda_\beta(B, c) T_\beta(B, c)$$

for every constant $c > 0$, where

$$\lambda_\beta(B, c) = \min \left\{ \frac{\int_B |\nabla u|^2 \, dx + \beta \int_{\partial B} u^2 \, d\mathcal{H}^{d-1} + c \int_B u^2 \, dx}{\int_B u^2 \, dx} : u \in H^1(B) \setminus \{0\} \right\}$$

and

$$T_\beta(B, c) = \max \left\{ \frac{(\int_B u \, dx)^2}{\int_B |\nabla u|^2 \, dx + \beta \int_{\partial B} u^2 \, d\mathcal{H}^{d-1} + c \int_B u^2 \, dx} : u \in H^1(B) \setminus \{0\} \right\}.$$

From the expressions above we obtain

$$\lambda_\beta(B, c) = \lambda_\beta(B) + c$$

and

$$T_\beta(B, c) \geq \frac{1}{\beta \mathcal{H}^{d-1}(\partial B) + c}.$$

Therefore, we have

$$M_1 \geq \frac{\lambda_\beta(B) + c}{\beta \mathcal{H}^{d-1}(\partial B) + c}$$

for every $c > 0$, and the inequality $M_1 \geq 1$ now follows by passing to the limit as $c \rightarrow +\infty$.

5. Open Questions and Remarks

In this section we raise a couple of open and challenging questions in the case $\beta < +\infty$ of Robin boundary conditions. Because of the lack of scaling property for the functional F_q , the proofs available in the Dirichlet case cannot be easily extended, and we believe it would be interesting to prove (or disprove) them.

The first question is concerned with the Kohler–Jobin inequality: in the Dirichlet case it reads as

$$m_q = F_q(B) \quad \text{for every } q \leq 2/(d+2).$$

We have seen in Theorem 4.1 that in the Robin case $\beta < +\infty$ the threshold (if any) cannot be the same because $m_q = 0$ for every $q > 1/(d+1)$. So the first question is:

(Q1) *in the Robin case $\beta < +\infty$, is it true that for every $q \leq 1/(d+1)$, or at least for q below a smaller threshold, the Kohler–Jobin inequality*

$$m_q = F_q(B)$$

holds?

A positive answer to the question (Q1) above would be rather natural since as $q \rightarrow 0$, the term T_β^q in the expression of the functional F_q , becomes less and less relevant, and the ball B actually minimizes the limit case $q = 0$, where F_q simply reduces to λ_β , as recalled in Sect. 2.

The second question is concerned with a possible analogous of Theorem 3.2 for M_q when q is large enough (reverse Kohler–Jobin inequality). We have seen that in the Dirichlet case $\beta = +\infty$ we have

$$M_q = F_q(B)$$

for every q above a suitable threshold $\bar{q}$. So, a natural question is:

(Q2) *in the Robin case $\beta < +\infty$, is it true that for every q above a suitable threshold $\bar{q}_\beta$ the reverse Kohler–Jobin inequality*

$$M_q = F_q(B)$$

holds?

Again, a positive answer to the question (Q2) above would be rather natural since as $q \rightarrow +\infty$ the term λ_β in the expression of the functional F_q , becomes less and less relevant, and the ball B actually maximizes the limit case $q = +\infty$, where F_q simply reduces to T_β , as recalled in Sect. 2.

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Appendix

The following appendix is devoted to the proof of (4.2).

Lemma 5.1. (Surface measure homogenization) *The measures μ_N converge in $H^{-1}(\mathbb{R}^d)$ to*

$$\mu = k^{d-1} d\omega_d \mathcal{L}^d$$

where ω_d is the volume of the unit ball in $\mathbb{R}^d$.

Proof. For the sake of brevity, we set

$$\nu_N = \mu_N - \mu.$$

A direct computation shows that ν_N tends to 0 narrowly; our aim is to show that $\|\nu_N\|_{H^{-1}(\mathbb{R}^d)} \rightarrow 0$. By construction it holds $\nu_N(\mathbb{R}^d) = 0$. We recall that the H^{-1} norm can be expressed as Fourier integral via

$$\|\nu_N\|_{H^{-1}(\mathbb{R}^d)}^2 = \int_{\mathbb{R}^d} \frac{|\widehat{\nu_N}|^2}{1 + |\xi|^2} d\xi.$$

Let us notice that $\widehat{\nu_N} \in C^\infty$ and $\widehat{\nu_N}(0) = 0$. In particular, the ratio $\frac{\widehat{\nu_N}(\xi)}{|\xi|}$ is bounded as $\xi \rightarrow 0$. Now, denoting by G the Green function of $-\Delta$ in $\mathbb{R}^d$ and recalling that $\widehat{G} = \frac{1}{|\xi|^2}$, we have

$$\int_{\mathbb{R}^d} \frac{|\widehat{\nu_N}|^2(\xi)}{|\xi|^2} d\xi = \langle \widehat{G} \widehat{\nu_N}, \widehat{\nu_N} \rangle \quad (5.1)$$

where $\langle \cdot, \cdot \rangle$ denotes the duality product between functions and measures. We thus get the thesis if the last right hand side tends to zero; equivalently, passing to the

antitransforms, we prove¹ that $\langle G * \nu_N, \nu_N \rangle \rightarrow 0$. This latter limit can be split as follows:

$$\langle G * \mu_N, \mu_N \rangle - 2\langle G * \mu, \mu_N \rangle + \langle G * \mu, \mu \rangle.$$

As $G * \mu$ is a C^1 function by elliptic regularity, and using the narrow convergence of μ_N to μ (and their compact support), it suffices to show that

$$\lim_{N \rightarrow +\infty} \langle G * \mu_N, \mu_N \rangle = \langle G * \mu, \mu \rangle. \quad (5.2)$$

To this aim, let us define, for any $\varepsilon > 0$, the continuous functions

$$G_\varepsilon(x) := [G(x) - G(\varepsilon)] 1_{\{|x| \geq \varepsilon\}}.$$

where, with a small abuse of notation, we denoted $G(|x|) = G(x)$ since G is radial. For any fixed $\varepsilon > 0$ it holds

$$\lim_{N \rightarrow +\infty} |\langle G_\varepsilon * \mu_N, \mu_N \rangle - \langle G_\varepsilon * \mu, \mu \rangle| = 0 \quad (5.3)$$

since the sequence $(G_\varepsilon * \mu_N)_N$ converges to $G_\varepsilon * \mu$ uniformly. Moreover, by monotone convergence, one gets

$$\lim_{\varepsilon \rightarrow 0} |\langle G_\varepsilon * \mu, \mu \rangle - \langle G * \mu, \mu \rangle| = 0 \quad (5.4)$$

It further holds

$$\begin{aligned} |\langle G_\varepsilon * \mu_N, \mu_N \rangle - \langle G * \mu_N, \mu_N \rangle| &\leq 2 \int_{\{|x-y| \leq \varepsilon\}} G(x-y) d\mu_N(x) d\mu_N(y) \\ &= 2 \sum_{\vec{\ell}} \int_{(\partial B(x_{\vec{\ell}}, r_N) \times \partial B(x_{\vec{\ell}}, r_N)) \cap \{|x-y| \leq \varepsilon\}} G(x-y) d\mathcal{H}^{d-1}(x) d\mathcal{H}^{d-1}(y) \\ &\quad + 2 \sum_{\vec{\ell} \neq \vec{p}} \int_{(\partial B(x_{\vec{\ell}}, r_N) \times \partial B(x_{\vec{p}}, r_N)) \cap \{|x-y| \leq \varepsilon\}} G(x-y) d\mathcal{H}^{d-1}(x) d\mathcal{H}^{d-1}(y) \end{aligned}$$

Let us split the analysis into off-diagonals and diagonal terms. We only discuss here the case $d \geq 3$. Concerning the off diagonal terms, we observe that, for any $i \neq j$ and N sufficiently large

$$|x - y| = |(x - x_i) - (y - x_j) + (x_{\vec{\ell}} - x_{\vec{p}})| \geq |x_{\vec{\ell}} - x_{\vec{p}}| - 2r_N = \frac{1}{N} - \frac{2k}{N^{\frac{d}{d-1}}} > \frac{1}{2N},$$

thus,

$$2\varepsilon \geq 2|x - y| \geq |x_{\vec{\ell}} - x_{\vec{p}}| = \frac{1}{N}.$$

We thus get

$$\sum_{\vec{\ell} \neq \vec{p}} \int_{\partial B(x_{\vec{\ell}}, r_N)} \int_{\partial B(x_{\vec{p}}, r_N)} G(x-y) 1_{\{|x-y| \leq \varepsilon\}} d\mathcal{H}^{d-1}(x) d\mathcal{H}^{d-1}(y)$$

¹for a rigorous justification of this anti-transformation, one may first consider mollifiers ϱ_ε and apply the Parseval identity to the duality between $G * (\varrho_\varepsilon * \nu_N)$, regarded as a tempered distribution, and the Schwartz function $\varrho_\varepsilon * \nu_N$; additionally, the formula for the Fourier transform of a convolution is justified in this setting, and, since $\widehat{\varrho_\varepsilon * \nu_N}$ is pointwise dominated by $\widehat{\nu_N}$, one may pass to the limit in the left-hand side of (5.1).

$$\begin{aligned}
&\leq 2^{d-2} \sum_{\vec{\ell} \neq \vec{p}} 1_{\{|x_{\vec{\ell}} - x_{\vec{p}}| \leq 2\varepsilon\}} \int_{\partial B(x_{\vec{\ell}}, r_N)} \int_{\partial B(x_{\vec{p}}, r_N)} \frac{1}{|x_{\vec{\ell}} - x_{\vec{p}}|^{d-2}} d\mathcal{H}^{d-1}(x) d\mathcal{H}^{d-1}(y) \\
&\leq \frac{2^{d-2} k^{d-1}}{N^{2d}} \sum_{\vec{\ell} \neq \vec{p}} \frac{1_{\{|x_{\vec{\ell}} - x_{\vec{p}}| \leq 2\varepsilon\}}}{|x_{\vec{\ell}} - x_{\vec{p}}|^{d-2}} = \frac{C}{N^d} \sum_{\vec{\ell}} \left(\frac{1}{N^d} \sum_{\vec{p}} \frac{1_{\{|x_{\vec{\ell}} - x_{\vec{p}}| \leq 2\varepsilon\}}}{|x_{\vec{\ell}} - x_{\vec{p}}|^{d-2}} \right) \\
&\leq \frac{C}{N^d} \sum_{\vec{p}} \frac{1_{\{|x_{\vec{\ell}} - x_{\vec{p}}| \leq 2\varepsilon\}}}{|x_{\vec{\ell}} - x_{\vec{p}}|^{d-2}}.
\end{aligned}$$

for an arbitrary choice of $\vec{\ell} \in \{1, \dots, N\}^d$, since the second sum gives by symmetry a result which is independent of $\vec{\ell}$. Now, the right-hand side above can be seen as a Riemann sum as $N \rightarrow +\infty$ for the integrable function $\frac{1}{|x_{\vec{\ell}} - x|^{d-2}}$, so that we get

$$\frac{1}{N^d} \sum_{\vec{p}} \frac{1_{\{|x_{\vec{\ell}} - x_{\vec{p}}| \leq 2\varepsilon\}}}{|x_{\vec{\ell}} - x_{\vec{p}}|^{d-2}} \rightarrow \int_{\{|x - x_{\vec{\ell}}| \leq 2\varepsilon\}} \frac{1}{|x - x_{\vec{\ell}}|^{d-2}} dx = C\varepsilon^2.$$

On the other hand, when N is large enough, with the change of variables $x = x_{\vec{\ell}} + r_N u$, $y = x_{\vec{\ell}} + r_N v$ the diagonal terms can be estimated with

$$\frac{1}{N^d} \int_{\mathbf{S}^{d-1} \times \mathbf{S}^{d-1}} \frac{1}{|u - v|^{d-2}} d\mathcal{H}^{d-1}(u) d\mathcal{H}^{d-1}(v) \rightarrow 0,$$

as the integral is finite thanks, for instance, to [28, Theorem 9.7].

Putting together the above estimates with (5.3) and (5.4), we get (5.2) by first letting $N \rightarrow +\infty$ and then $\varepsilon \rightarrow 0$, and this concludes the proof. $\square$

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